Multithreaded Algorithms for Approx and Exact Matching in Graphs

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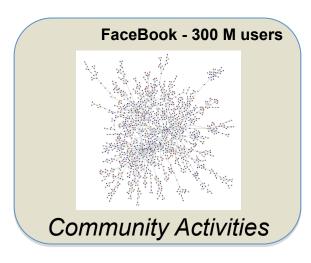
¹ Pacific Northwest National Laboratory
² Purdue University
³ Conviva Inc.

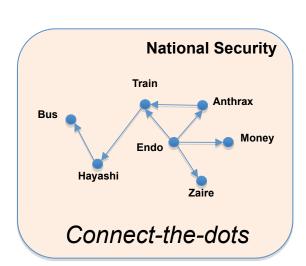
26 January, 2011

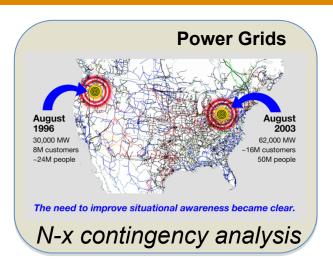
First ICCS Workshop

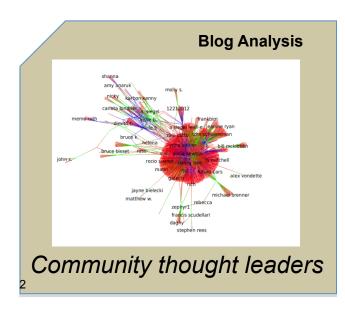


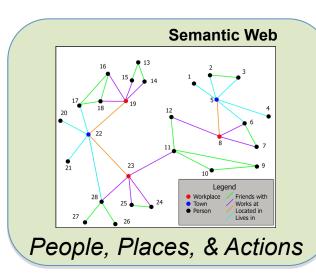
Motivation: Irregular applications

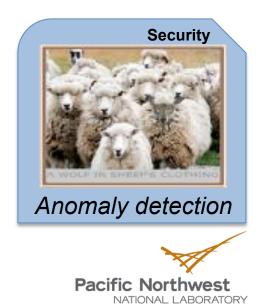












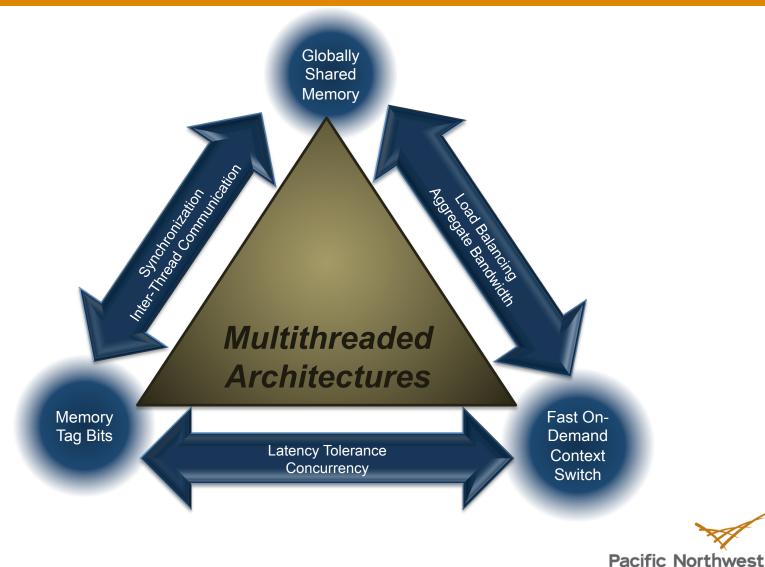
Proudly Operated by Battelle Since 1965

Challenges

- Problem size
 - Ton of bytes, not ton of flops
- Little data locality
 - Have only parallelism to tolerate latencies
- Low computation to communication ratio
 - Single word access
 - Threads limited by loads and stores
- Synchronization points are simple elements
 - Node, edge, record
- Work tends to be dynamic and imbalanced
 - Let any processor execute any thread



Key Architectural Features

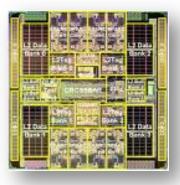


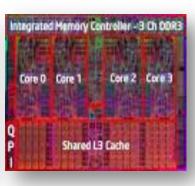


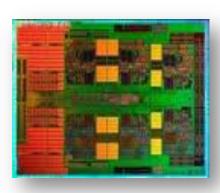
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Overview









XMT

Niagara-2

Nehalem

Magny-Cours

Multithreading

Caching

Approx Algorithms:

- Queue-based
- Q + Sorting
- Dataflow

Exact Algorithms

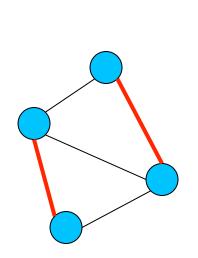
Input:

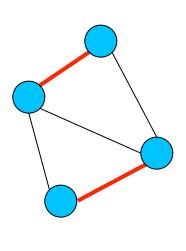
- ► RMAT-ER
- ► RMAT-G
- ► RMAT-B

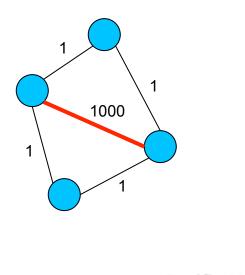


Matching

- ► A matching M is a subset of edges such that no two edges in M are incident on the same vertex
- Maximum matching maximizes some function
 - Number of edges matched (cardinality)
 - Sum or product of edge-weights

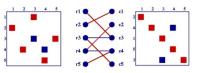




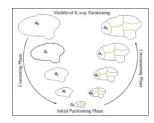


Applications of matching

- Sparse linear solvers
- Block triangular form
- Graph partitioners
- Bioinformatics
- Web technology
- High speed network switching
- **...**









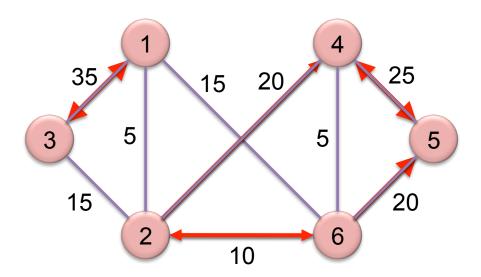


Algorithms

- Exact Algorithms:
 - Polynomial time algorithm first due to Edmonds
 - Maximum matching: Hopcroft-Karp
 - Maximum weighted: Hungarian
- (half) Approx Algorithms:
 - Sorting-based approaches (Global)
 - Search-based approaches (Local)
 - Preis's algorithm and its variants (Hoepman; Manne and Bisseling)

Pointer-based algorithm (Queue-based)

- Identify locally-dominant edges using pointers
- Implement with queues (queue matched vertices)
- Variant: sorted edge-sets

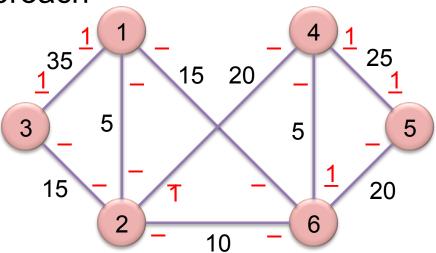




Pointer-based algorithm (Dataflow)

Queue headers can hotspot

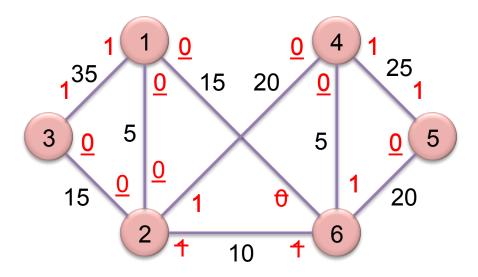
Dataflow approach



- Each node sets signal on its side of heaviest edge to 1
- Reads companion signal



Dataflow (cont.)

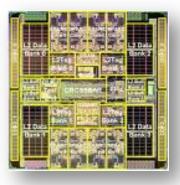


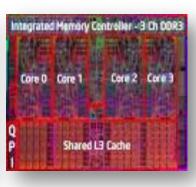
- If companion signal is 1, then set signal of other edges to 0 and stop
- else set signal on next heaviest edge to 1

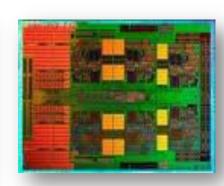


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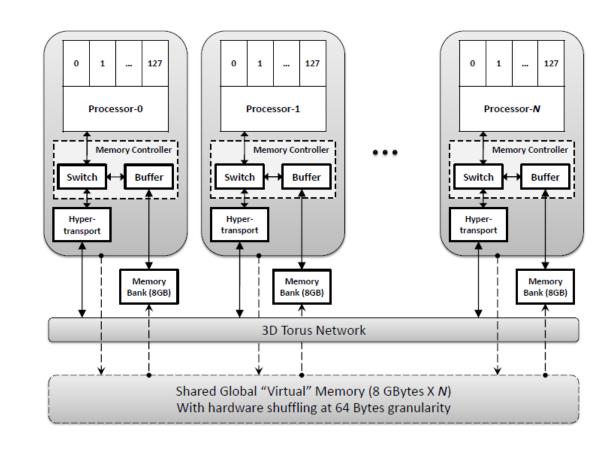
Input:

- ► RMAT-ER
- ► RMAT-G
- ► RMAT-B



Cray XMT: A block view

- Threadstorm Processor:
 - 500 MHz
 - 128 thread-streams
 - VLIW
- ► 8 GB/proc
- 3D Torus Interconnect

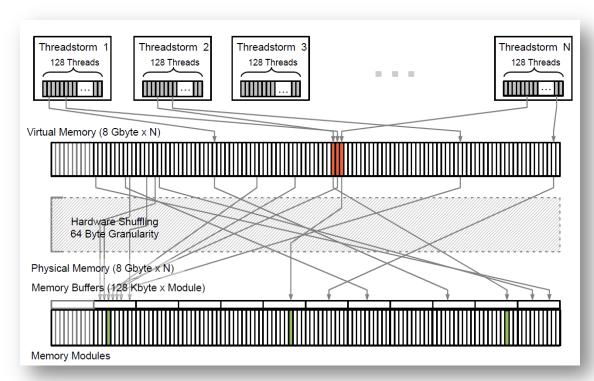




Cray XMT: Memory

Physically distributed, globally addressable

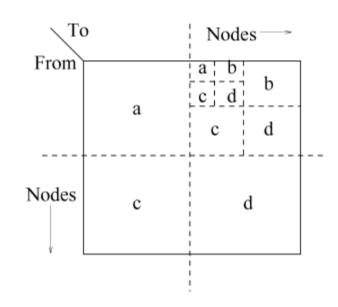
- ► 8 GB/proc
- ► Total = 1TB (128p)
- Byte addressable
- H/w hashing
- 64Byte granularity
- Worst-case latency is 1000 cycles
- Sustainable 60 Megawords/s per processor





Datasets: Synthetic data with R-MAT

- R-MAT: Recursive MATrix method
- Experiments
 - RMAT-ER (0.25, 0.25, 0.25, 0.25)
 - RMAT-G (0.45, 0.15, 0.15, 0.25)
 - RMAT-B (0.55, 0.15, 0.15, 0.15)

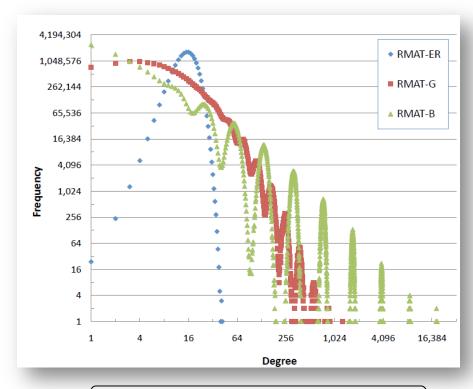


Chakrabarti, D. and Faloutsos, C. 2006. Graph mining: Laws, generators, and algorithms. *ACM Comput. Surv.* 38, 1 (Jun. 2006), 2.



Datasets for experiments

Graph	No. Vertices	No. Edges	Avg. Degree	Max Degree	Variance	Avg. Clustering Coeff.
RMAT-ER	16,777,216	134, 217, 654	16	42	16.01	10.0e - 7
RMAT-G	16,777,216	134, 181, 095	16	1,278	415.72	12.0e - 6
RMAT-B	16,777,216	133,658,229	16	38,143	8,085.64	34.3e - 5



16,777,216 ■ RMAT-ER 4,194,304 ■ RMAT-G 1,048,576 262,144 RMAT-B 65,536 16,384 Frequency 4,096 1,024 256 64 16 (0 to 0.25) (0.25 to 0.50) (0.50 to 0.75) (0.75 to 1.00) zero Local clustering coefficient

Degree distribution

Clustering coefficient

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Experimental Results

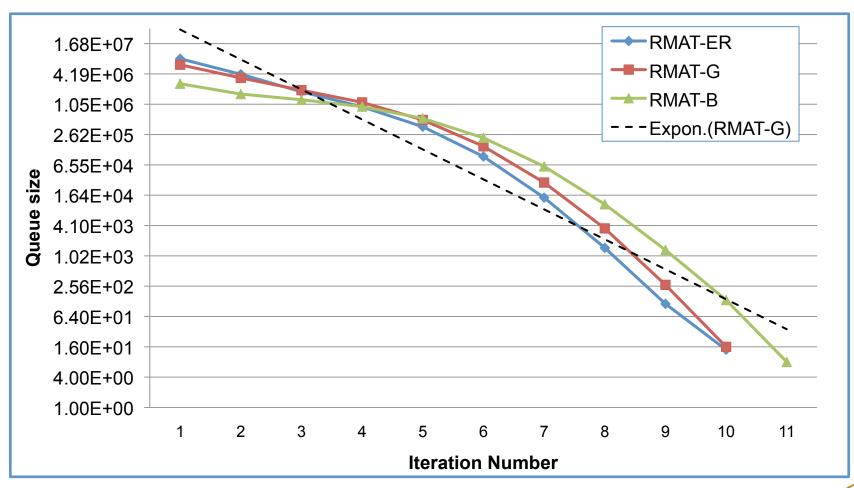
- ½-approx algorithm
- Magny-cours, Nehalem, Niagara-2, XMT
- RMAT-B

Matching: Cardinality

Graph	Init. (% of final card)	Final (% of V)
RMAT-ER	53.14%	94.12
RMAT-G	46.33%	81.70%
RMAT-B	36.06%	44.24%



Matching: Queue status

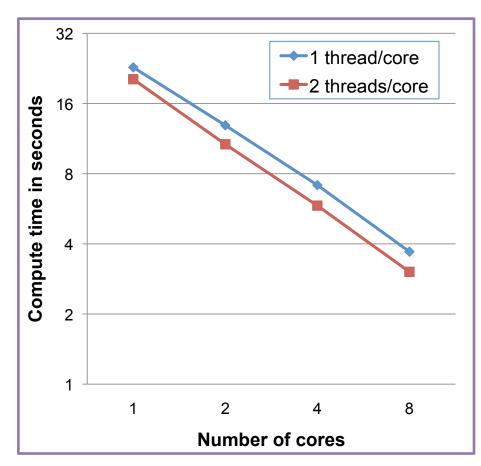


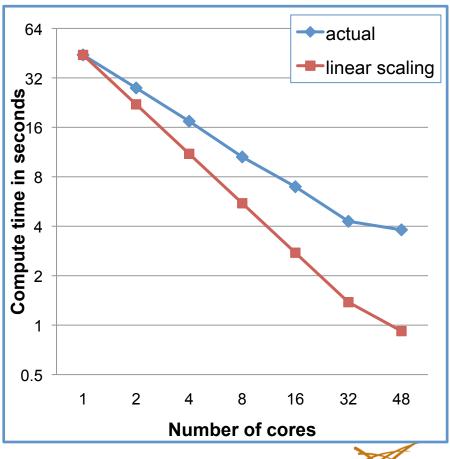
Strong scaling: Nehalem & Magny-Cours

Nehalem

RMAT-B

Magny-Cours





Algorithm: Queue-based

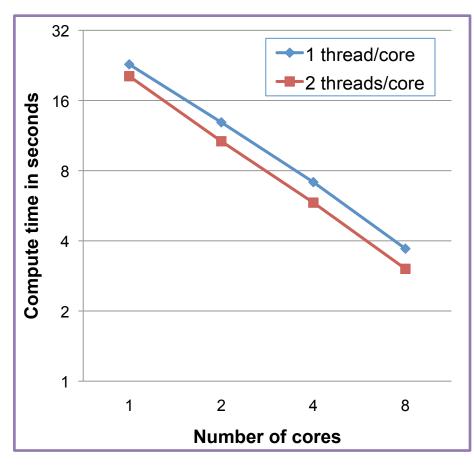


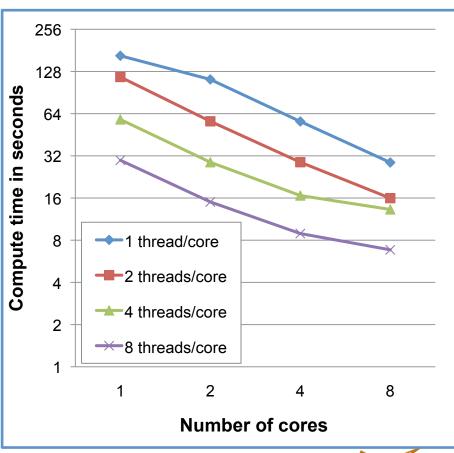
Strong scaling: Nehalem & Niagara-2

Nehalem

RMAT-B

Niagara-2



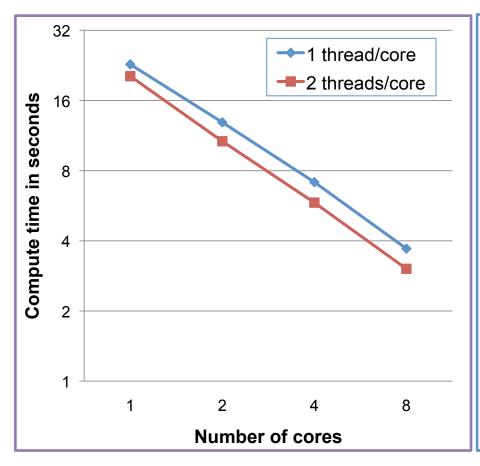


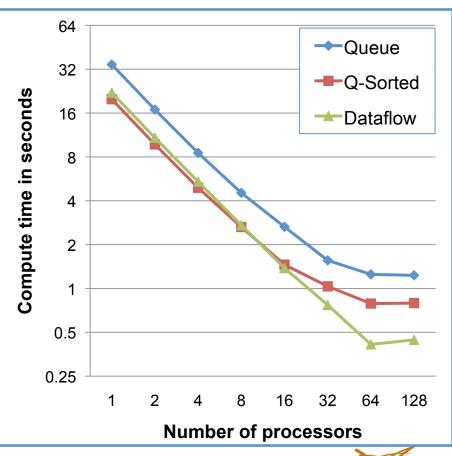
Algorithm: Queue-based



Strong scaling: Nehalem & XMT

Nehalem RMAT-B XMT



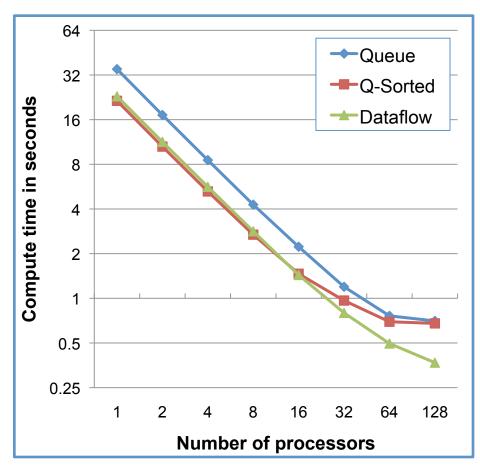


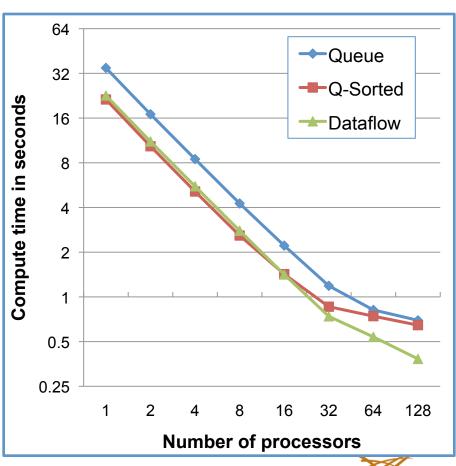
Algorithm: Queue; Q-Sorted; Dataflow



Strong scaling: XMT

RMAT-ER RMAT-B





Algorithm: Queue; Q-Sorted; Dataflow



Exact matching

- Augmentation-based approach
- Single-path v/s Multiple-path
- Hopcroft-Karp algorithm:
 - Breadth-first + Depth-first
 - Dynamic: amount and type of parallelism
 - Nested loop structure
- Our approach:
 - Different locking policies (first-visited, last-, random)
 - Disjoint forest (merge BFS+DFS)
- Future: Use futures :-)



Summary & conclusion: The trinity

